Conference Chair
Prof. Yoshifumi Manabe, Faculty of Informatics,
Kogakuin University, Tokyo, Japan

Technical Program Chair
Prof. Yen-Wei Chen, Ritsumeikan University, Japan

Submission Method
Please submit your full paper or abstract via
Easychair Submission System:
https://easychair.org/conferences/?conf=icrit2018

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Publication
Submissions will be reviewed by the conference committees and journal editorial board, and accepted papers will be published in International Journal of Mechanical Engineering and Robotics Research as a special issue, which will be indexed by Index Corpernicus, ProQuest, UDL, Google Scholar, Open J-Gate, Scopus (since 2016) etc..

Important Dates
Submission Deadline: April 5, 2018
Notification Date: April 20, 2018
Registration Deadline: May 5, 2018
Conference Dates: May 24-26, 2018

Call for Papers

Robot Design, Development and Control
Control and Supervision Systems
Telerobotics and Teleoperation
Vehicle Control Applications
Industrial Networks and Automation
Human-Robots Interfaces
Network Robotics
Autonomous Agents
Intelligent Transportation Technologies and Systems
Space and Underwater Robots
Modelling, Simulation and Architecture
Human-Machine Interfaces
Collective and Social Robots
Humanoid Robots
Cognitive Approach for Robotics
Mobile Robots and Intelligent Autonomous Systems
Mechatronics Systems
Virtual Environment, Virtual and Augmented Reality

Perception and Awareness
Surveillance, Fault detection and Diagnosis
Engineering Applications
Genetic Algorithms
Fuzzy Control
Decision Support Systems
Machine Learning in Control Applications
Knowledge-based Systems Applications
Hybrid Learning Systems
Distributed Control Systems
Evolutionary Computation and Control
Optimization Algorithms
Soft Computing
Software Agents for Intelligent Control Systems
Neural Networks based Control Systems
Planning and Scheduling
Intelligent Fault Detection and Diagnosis
Engineering Application